

Virtual Laboratory

A segment coordinate system in Visual3D does not have to be associated with the subject, or even with motion capture data for that matter. We refer to these as virtual segments. **The only distinction between virtual segments and real segments is that typically we set them to be *Kinematic only* segments, which means that they are not included in the Inverse Dynamics calculations.** In all other ways they are just segments and are constructed with the same rules as all segments.

Example: Simple Virtual Laboratory

A Virtual Laboratory is not a physical segment in Visual3D but is equivalent to a physical segment to the effect that it has a Segment Coordinate System that can be used to represent the laboratory (or other objects) and has an associated surface model that can be animated as part of the scene. A typical use of the Virtual Laboratory is to represent the floor so that motion capture markers can be projected onto the floor.

Note: A typical use of the Virtual laboratory is for creating [Normalized Joint Angles and Normalized Segment Angles](#).

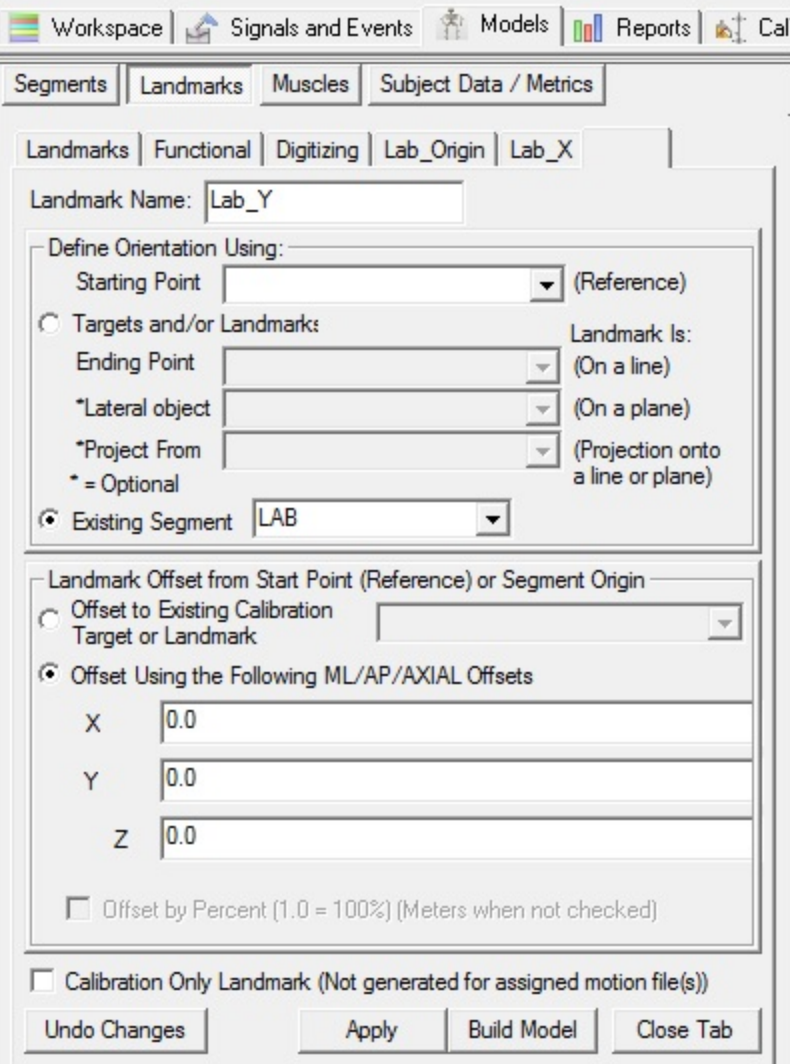
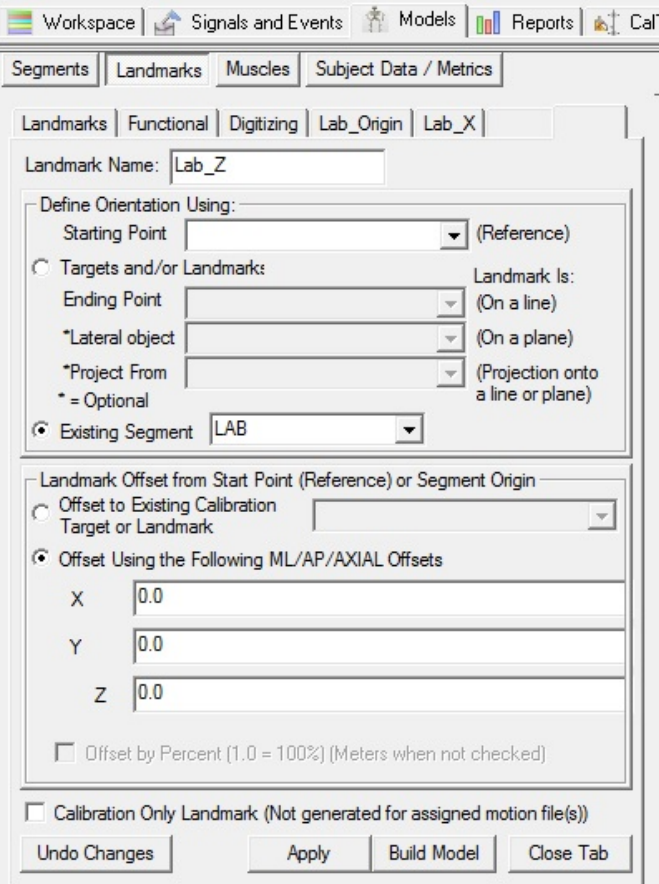
Below is a straightforward virtual lab that has a specified constant orientation.

An example of the Simple Virtual Lab can be downloaded [here](#).

Create 4 Landmarks

First, create 4 landmarks **Lab_Origin**, **Lab_X**, **Lab_Y**, and **Lab_Z**. To create these landmarks, go to the **Model** tab and select the **Landmarks** tab.

1. Create Lab_Origin: • Click Landmarks button • Click Add New Landmark button • Create Landmark: Lab_Origin	Landmark Name: Lab_Origin Define Orientation Using: Starting Point Leave Blank Existing Segment: LAB	• Offset Using the Following ML/AP/AXIAL Offsets: X: 0.0 Y: 0.0 Z: 0.0 • DO NOT Check: Offset by Percent (1.0 = 100%) • DO NOT Check: Calibration Only Landmark	Workspace Signals and Events Models Reports Cal Segments Landmarks Muscles Subject Data / Metrics Landmarks Functional Digitizing Lab_Origin Landmark Name: Lab_Origin Define Orientation Using: Starting Point (Reference) Targets and/or Landmarks: Ending Point (On a line) *Lateral object (On a plane) *Project From (Projection onto a line or plane) * = Optional Existing Segment LAB Landmark Offset from Start Point (Reference) or Segment Origin Offset to Existing Calibration Target or Landmark Offset Using the Following ML/AP/AXIAL Offsets X 0.0 Y 0.0 Z 0.0 Offset by Percent (1.0 = 100%) (Meters when not checked) Calibration Only Landmark (Not generated for assigned motion file(s)) Undo Changes Apply Build Model Close Tab
2. Create Lab_X: • Click Landmarks button • Click Add New Landmark button • Create Landmark: Lab_X	Landmark Name: Lab_X Define Orientation Using: Starting Point Leave Blank Existing Segment: LAB	• Offset Using the Following ML/AP/AXIAL Offsets: X: 0.1 Y: 0.0 Z: 0.0 • DO NOT Check: Offset by Percent (1.0 = 100%) • DO NOT Check: Calibration Only Landmark	Workspace Signals and Events Models Reports Cal Segments Landmarks Muscles Subject Data / Metrics Landmarks Functional Digitizing Lab_Origin Landmark Name: Lab_X Define Orientation Using: Starting Point (Reference) Targets and/or Landmarks: Ending Point (On a line) *Lateral object (On a plane) *Project From (Projection onto a line or plane) * = Optional Existing Segment LAB Landmark Offset from Start Point (Reference) or Segment Origin Offset to Existing Calibration Target or Landmark Offset Using the Following ML/AP/AXIAL Offsets X 0.0 Y 0.0 Z 0.0 Offset by Percent (1.0 = 100%) (Meters when not checked) Calibration Only Landmark (Not generated for assigned motion file(s)) Undo Changes Apply Build Model Close Tab

3. Create Lab_Y: - Click Landmarks button - Click Add New Landmark button - Create Landmark: <i>Lab_Y</i>	Landmark Name: <i>Lab_Y</i> Define Orientation Using: Starting Point: <i>Leave Blank</i> Existing Segment: <i>LAB</i>	- Offset Using the Following ML/AP/AXIAL Offsets: X: 0.0 Y: 0.1 Z: 0.0 DO NOT Check: <i>Offset by Percent (1.0 = 100%)</i> DO NOT Check: <i>Calibration Only Landmark</i>	
4. Create Lab_Z: - Click Landmarks button - Click Add New Landmark button - Create Landmark: <i>Lab_Z</i>	Landmark Name: <i>Lab_Z</i> Define Orientation Using: Starting Point: <i>Leave Blank</i> Existing Segment: <i>LAB</i>	- Offset Using the Following ML/AP/AXIAL Offsets: X: 0.0 Y: 0.0 Z: 0.1 DO NOT Check: <i>Offset by Percent (1.0 = 100%)</i> DO NOT Check: <i>Calibration Only Landmark</i>	

A subset of 3 of these Landmarks can be used to represent the Segment Coordinate System

Create the Virtual Laboratory Segment

To create the Virtual Laboratory segment, switch to the **Segment** Tab in model builder mode.

1. Create the Virtual Lab Segment:

1. In the Segment Name combo box type **Virtual Lab**

2. Check the **Kinematic Only** Check Box

3. Select the **Create** button

4. In the **Virtual Lab** tab, enter these values:

Define Proximal Joint and Radius

Lateral: *None*

Joint: *Lab_Z*

Medial: *None*

Radius: 0.01

Define Distal Joint and Radius

Lateral: *None*

Joint: *Lab_Origin*

Medial: *None*

Radius: 0.01

Extra Target to define Orientation

Select: *Lateral Lab_X*

Select Tracking Targets:

Check: Use Calibration Targets for Tracking

5. Click on **Build Model**.

6. Click on **Close Tab** before proceeding.

Workspace | Signals and Events | Models | Reports | Cal

Segments | Landmarks | Muscles | Subject Data / Metrics

Segments | Segment Properties | IK Constraints

Segment Name
Virtual Lab

Segment Type
Visual 3D

☒ Kinematic Only

Create

Workspace | Signals and Events | Models | Reports | CalTester | Real-Time | IAA

Segments | Landmarks | Muscles | Subject Data / Metrics | Virtual Lab

Define Proximal Joint and Radius

Lateral: *None*

Joint Center: *Lab_Z*

Medial: *None*

Radius (Meters): 0.01

Define Distal Joint and Radius

Lateral: *None*

Joint Center: *Lab_Origin*

Medial: *None*

Radius (Meters): 0.01

Extra Target to Define Orientation (if needed)

Location: *Lateral*

Lab_X

Select Tracking Targets (Ctrl-Left Mouse Click to Multiselect)

☒ Use Calibration Targets for Tracking

Depth (Meters):

Close Tab

Guess Properties

Apply

Build Model

Visual3D v6 Prof

Adding a Surface Model

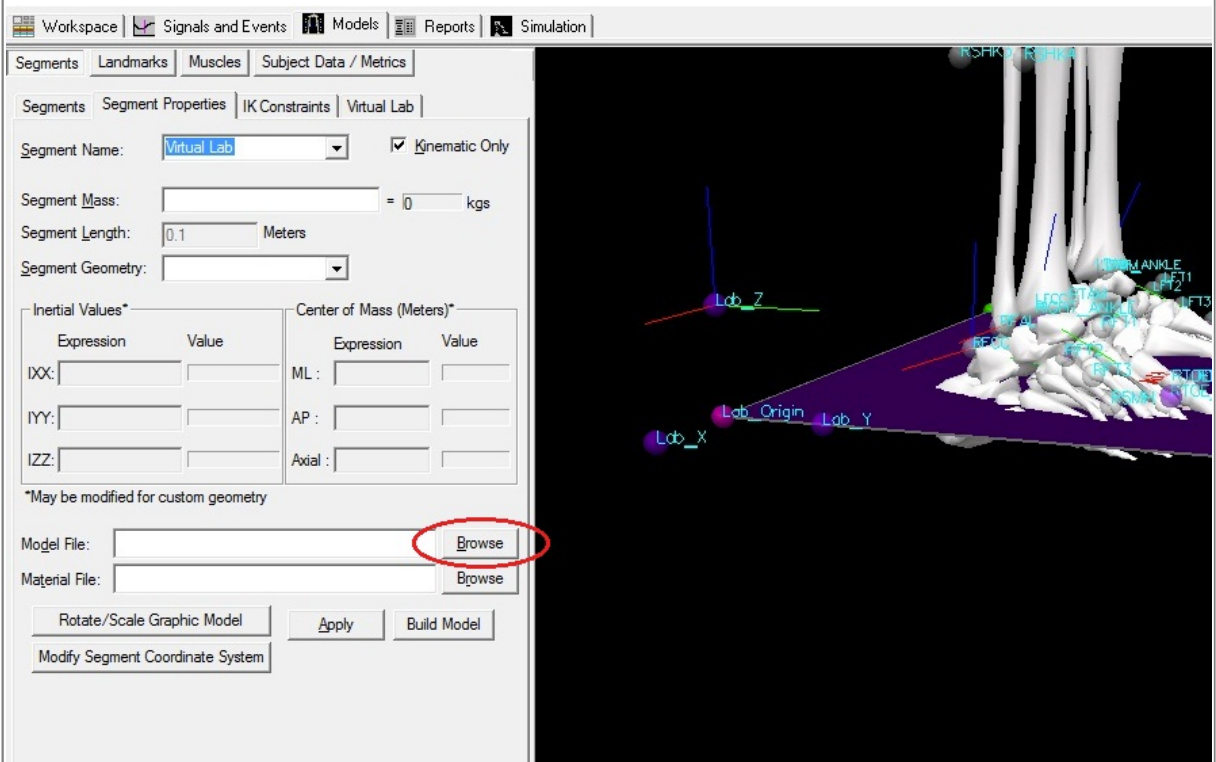
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To add a surface model or graphic switch to the **Segment Properties** Tab. Select **Virtual Lab** as Segment Name. Near the bottom of the dialog **Browse** for a Model File (.obj or .v3g) of your choosing.

Select **Apply**.

Note: A surface model need not be applied to the virtual lab.



Example: Virtual segment aligned with a different principal axis of the laboratory

The following example will construct a segment coordinate system that is rotated from the laboratory coordinate system.

An example of a Rotated Virtual Lab can be downloaded [here](#).

Create 3 Landmarks

First, create 3 landmarks **Lab_Origin**, **Lab_Other**, and **Lab_Z**. To create these landmarks, go to the **Model** tab and select the **Landmarks** tab.

1. Create Lab-Origin: • Click Landmarks button • Click Add New Landmark button • Create Landmark: Lab-Origin	Landmark Name: Lab-Origin Define Orientation Using: Starting Point: Leave Blank Existing Segment: LAB	• Offset Using the Following ML/AP/AXIAL Offsets: X: 0.0 Y: 0.0 Z: 0.0 • DO NOT Check: Offset by Percent (1.0 = 100%) • DO NOT Check: Calibration Only Landmark	Workspace Signals and Events Models Reports Cal Segments Landmarks Muscles Subject Data / Metrics Landmarks Functional Digitizing Lab-Origin Landmark Name: Lab-Origin Define Orientation Using: Starting Point (Reference) Targets and/or Landmarks: Ending Point (On a line) *Lateral object (On a plane) *Project From (Projection onto a line or plane) * = Optional Existing Segment LAB Landmark Offset from Start Point (Reference) or Segment Origin Offset to Existing Calibration Target or Landmark Offset Using the Following ML/AP/AXIAL Offsets X 0.0 Y 0.0 Z 0.0 Offset by Percent (1.0 = 100%) (Meters when not checked) Calibration Only Landmark (Not generated for assigned motion file(s)) Undo Changes Apply Build Model Close Tab
2. Create Lab-Other: • Click Landmarks button • Click Add New Landmark button • Create Landmark: Lab-Other	Landmark Name: Lab-Other Define Orientation Using: Starting Point: Leave Blank Existing Segment: LAB	• Offset Using the Following ML/AP/AXIAL Offsets: X: 0.0 Y: 0.1 Z: 0.0 • DO NOT Check: Offset by Percent (1.0 = 100%) • DO NOT Check: Calibration Only Landmark	Workspace Signals and Events Models Reports Cal Segments Landmarks Muscles Subject Data / Metrics Landmarks Functional Digitizing Lab-Origin Lab-Other Landmark Name: Lab-Other Define Orientation Using: Starting Point (Reference) Targets and/or Landmarks: Ending Point (On a line) *Lateral object (On a plane) *Project From (Projection onto a line or plane) * = Optional Existing Segment LAB Landmark Offset from Start Point (Reference) or Segment Origin Offset to Existing Calibration Target or Landmark Offset Using the Following ML/AP/AXIAL Offsets X 0.0 Y 0.1 Z 0.0 Offset by Percent (1.0 = 100%) (Meters when not checked) Calibration Only Landmark (Not generated for assigned motion file(s)) Undo Changes Apply Build Model Close Tab

3. Create Lab_Z: - Click Landmarks button - Click Add New Landmark button - Create Landmark: Lab_Z	Landmark Name: Lab_Z Define Orientation Using: Starting Point: Existing Segment: LAB	- Offset Using the Following ML/AP/AXIAL Offsets: X: 0.0 Y: 0.0 Z: 0.1 DO NOT Check: <i>Offset by Percent (1.0 = 100%)</i> DO NOT Check: <i>Calibration Only Landmark</i>	
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Create the Virtual Laboratory Segment

To create the Virtual Laboratory segment, switch to the **Segment** Tab in model builder mode and enter the following:

1. Create the Virtual Lab Segment: - In the Segment Name combo box type Virtual Lab - Check the Kinematic Only Check Box - Select the Create button	
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4. In the **Virtual Lab** tab, enter these values:

Define Proximal Joint and Radius

Lateral: **None**

Joint: **Lab_Z**

Medial: **None**

Radius: 0.01

Define Distal Joint and Radius

Lateral: **None**

Joint: **Lab-Origin**

Medial: **None**

Radius: 0.01

Extra Target to define Orientation

Select: **Lateral** **Lab_Other**

Select Tracking Targets:

Check: Use Calibration Targets for Tracking

5. Click on **Build Model**.

6. Click on **Close Tab** before proceeding.

Workspace | Signals and Events | Models | Reports | Simulation

Segments | Landmarks | Muscles | Subject Data / Metrics

Segments | Segment Properties | IK Constraints | Virtual Lab

Define Proximal Joint and Radius

Lateral: **None**

Joint: **Lab_Z**

Medial: **None**

Radius (Meters): 0.01

Define Distal Joint and Radius

Lateral: **None**

Joint: **Lab-Origin**

Medial: **None**

Radius (Meters): 0.01

Extra Target to Define Orientation (if needed)

Location: **Lateral**

Lab_Other

Select Tracking Targets (Ctrl-Left Mouse Click to Multiselect)

☒ Use Calibration Targets for Tracking

Depth (Meters):

Close Tab

Guess Properties

Apply

Build Model

3D visualization of a virtual lab setup showing a 3D model of a human leg and foot, with various coordinate systems and landmarks labeled. The lab is defined relative to the lateral direction of the pelvis segment.

We have just created a virtual lab that is aligned with a different axis of the lab coordinate system (rotated).

Example: Creating a virtual laboratory that changes with the direction of walking

In this example file (Example3.cmo) the subject is walking in the anterior direction in one walking trial and walking in the posterior direction of the laboratory coordinate system (LAB) in the other trial. If the pelvis angle is defined as the pelvis with respect to the laboratory, the data are rotated 180 degrees from the desired angle for one of the trials (see *Pelvis Angle wrt Lab*). To create a pelvis angle that makes intuitive sense (e.g. in the direction of walking), a virtual lab segment was created. The pelvis angle can then be defined with respect to the virtual lab (see *Pelvis Angle wrt Virtual Lab*). In Example2.cmo the virtual laboratory was defined statically. But, in this example (Example3.cmo), the Virtual lab is defined relative to the lateral direction of the pelvis segment; the lateral direction is forced to lie along one of the principal axes rather than to float with the pelvis.

An example of a Virtual Lab which changes with the direction of walking can be downloaded [here](#).

See Also [A virtual lab with 4 possible orientations](#)

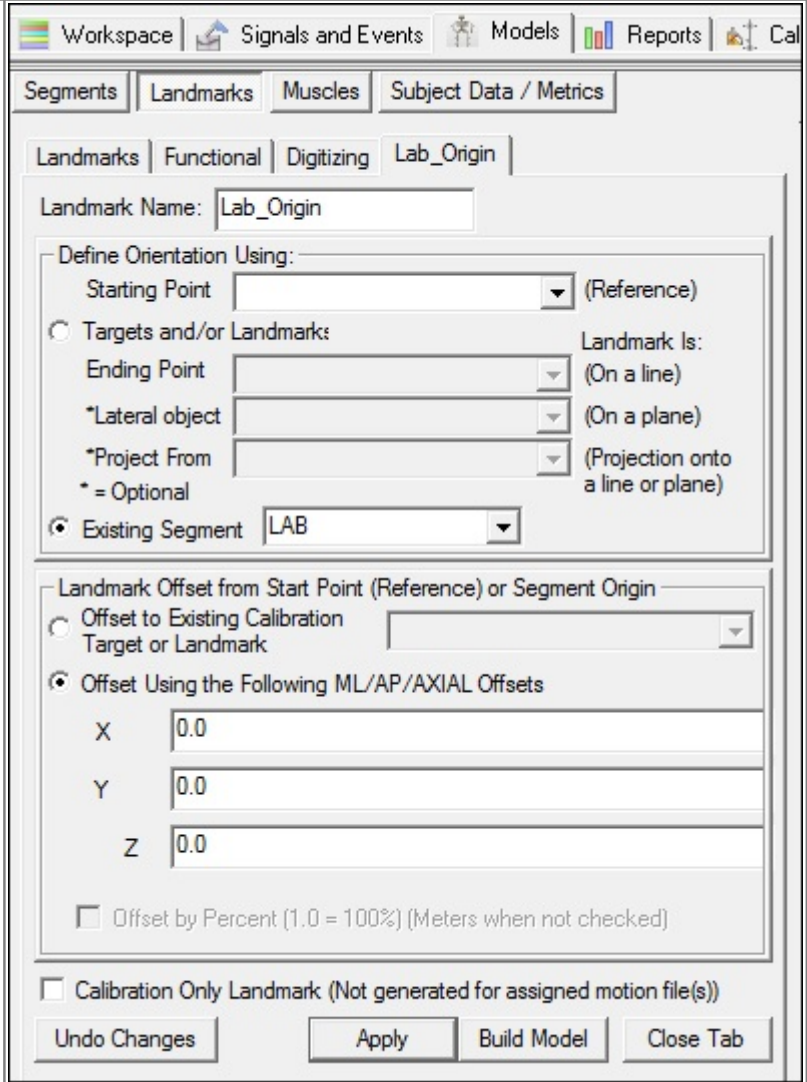
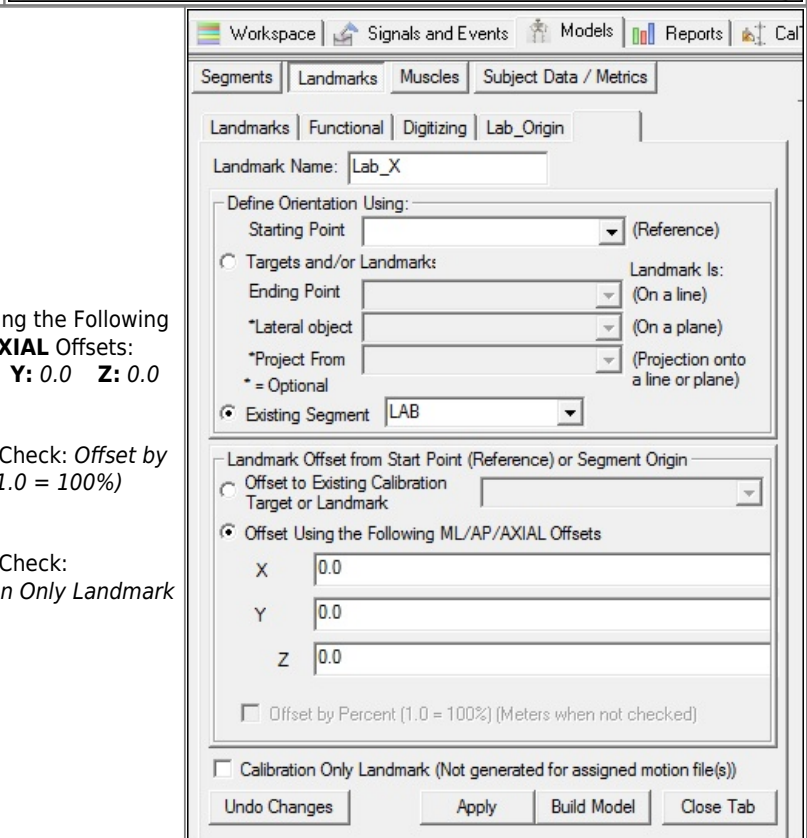
Create 3 Landmarks

Create 2 landmarks **Lab-Origin**, **Lab_X**, and **Lab_Z**. To create these landmarks, go to the **Model** tab

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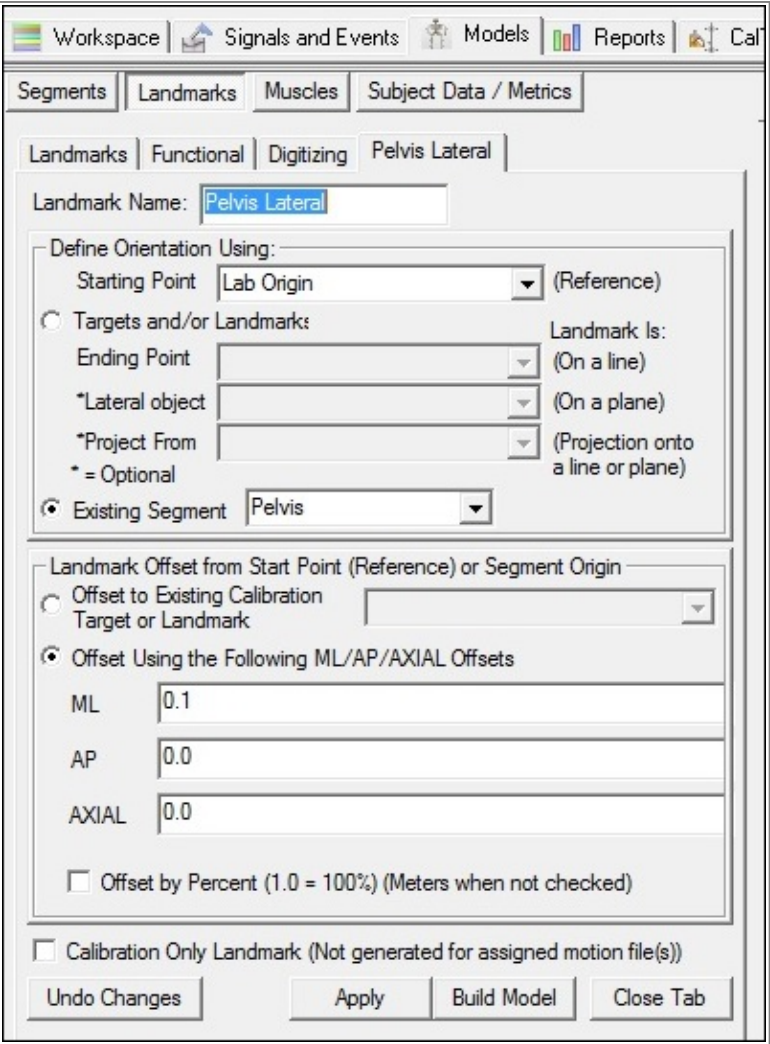
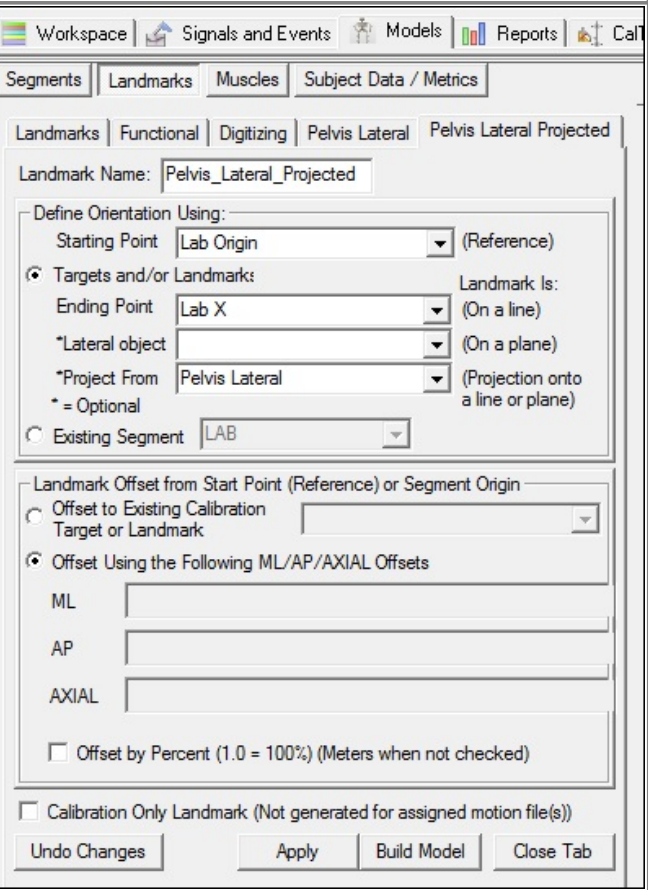
and select the **Landmarks** tab.

1. Create Lab_Origin: - Click Landmarks button - Click Add New Landmark button - Create Landmark: <i>Lab_Origin</i>	Landmark Name: <i>Lab_Origin</i> Define Orientation Using: Starting Point: <i>Leave Blank</i> Existing Segment: <i>LAB</i>	- Offset Using the Following ML/AP/AXIAL Offsets: X: 0.0 Y: 0.0 Z: 0.0 DO NOT Check: <i>Offset by Percent (1.0 = 100%)</i> DO NOT Check: <i>Calibration Only Landmark</i>	
2. Create Lab_X: - Click Landmarks button - Click Add New Landmark button - Create Landmark: <i>Lab_X</i>	Landmark Name: <i>Lab_Other</i> Define Orientation Using: Starting Point: <i>Leave Blank</i> Existing Segment: <i>LAB</i>	- Offset Using the Following ML/AP/AXIAL Offsets: X: 0.1 Y: 0.0 Z: 0.0 DO NOT Check: <i>Offset by Percent (1.0 = 100%)</i> DO NOT Check: <i>Calibration Only Landmark</i>	

3. Create Lab_Z: • Click Landmarks button • Click Add New Landmark button • Create Landmark: Lab_Z	Landmark Name: Lab_Z Define Orientation Using: Starting Point (Reference) Targets and/or Landmarks: Ending Point (On a line) *Lateral object (On a plane) *Project From (Projection onto a line or plane) * = Optional Existing Segment LAB Landmark Offset from Start Point (Reference) or Segment Origin Offset to Existing Calibration Target or Landmark Offset Using the Following ML/AP/AXIAL Offsets X 0.0 Y 0.0 Z 0.0 Offset by Percent (1.0 = 100%) (Meters when not checked) Calibration Only Landmark (Not generated for assigned motion file(s)) Undo Changes Apply Build Model Close Tab	• Offset Using the Following ML/AP/AXIAL Offsets: X: 0.0 Y: 0.0 Z: 0.1 • DO NOT Check: Offset by Percent (1.0 = 100%) • DO NOT Check: Calibration Only Landmark	Workspace Signals and Events Models Reports Cal Segments Landmarks Muscles Subject Data / Metrics Landmarks Functional Digitizing Lab_Origin Lab_X Landmark Name: Lab_Z Define Orientation Using: Starting Point (Reference) Targets and/or Landmarks: Ending Point (On a line) *Lateral object (On a plane) *Project From (Projection onto a line or plane) * = Optional Existing Segment LAB Landmark Offset from Start Point (Reference) or Segment Origin Offset to Existing Calibration Target or Landmark Offset Using the Following ML/AP/AXIAL Offsets X 0.0 Y 0.0 Z 0.0 Offset by Percent (1.0 = 100%) (Meters when not checked) Calibration Only Landmark (Not generated for assigned motion file(s)) Undo Changes Apply Build Model Close Tab
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Create a Landmark from the Pelvis lateral axis projected onto a Laboratory Axis

Create a landmark **Pelvis_Lateral** 10 cm from the Laboratory Origin in the lateral direction of the Pelvis. Create another landmark **Pelvis_Lateral_Projected** that projects **Pelvis_Lateral** onto a line formed by the **Lab_Origin** and **Lab_X** landmarks. Then create a landmark

1. Create Pelvis_Lateral: - Click Landmarks button - Click Add New Landmark button - Create Landmark: <i>Pelvis_Lateral</i>	Landmark Name: <i>Pelvis_Lateral</i> Define Orientation Using: Starting Point: <i>Lab_Origin</i> Existing Segment: <i>Pelvis</i>	- Offset Using the Following ML/AP/AXIAL Offsets: X: 0.1 Y: 0.0 Z: 0.0 DO NOT Check: <i>Offset by Percent (1.0 = 100%)</i> DO NOT Check: <i>Calibration Only Landmark</i>	
2. Create Pelvis_Lateral_Project: - Click Landmarks button - Click Add New Landmark button - Create Landmark: <i>Pelvis_Lateral_Project</i>	Landmark Name: <i>Pelvis_Lateral_Project</i> Define Orientation Using: Starting Point: <i>Lab_Origin</i> Ending Point: <i>Lab_X</i> Project From: <i>Pelvis_Lateral</i>	DO NOT Check: <i>Offset by Percent (1.0 = 100%)</i> DO NOT Check: <i>Calibration Only Landmark</i>	

3. Create Lab_Lateral: • Click Landmarks button • Click Add New Landmark button • Create Landmark: Lab_Lateral	Landmark Name: Lab_Lateral Define Orientation Using: Starting Point: Lab_Origin Ending Point: Pelvis_Lateral_Projected	• Offset Using the Following AXIAL Offset: 0.1 • DO NOT Check: Offset by Percent (1.0 = 100%) • DO NOT Check: Calibration Only Landmark	Workspace Signals and Events Models Reports Cal Segments Landmarks Muscles Subject Data / Metrics Digitizing Pelvis Lateral Pelvis Lateral Projected Lab Lateral Landmark Name: Lab_Lateral Define Orientation Using: Starting Point: Lab_Origin (Reference) • Targets and/or Landmark: Ending Point: Pelvis_Lateral_Projected (On a line) *Lateral object (On a plane) *Project From (Projection onto a line or plane) * = Optional Existing Segment: LAB Landmark Offset from Start Point (Reference) or Segment Origin Offset to Existing Calibration Target or Landmark • Offset Using the Following ML/AP/AXIAL Offsets ML AP AXIAL 0.1 Offset by Percent (1.0 = 100%) (Meters when not checked) Calibration Only Landmark (Not generated for assigned motion file(s)) Undo Changes Apply Build Model Close Tab
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Create Virtual Laboratory Segment

To create the Virtual Laboratory segment, switch to the **Segment** Tab in model builder mode and enter the following:

1. Create the Virtual Lab Segment: 1. In the Segment Name combo box type Virtual Lab 2. Check the Kinematic Only Check Box 3. Select the Create button	Workspace Signals and Events Models Reports Cal Segments Landmarks Muscles Subject Data / Metrics Segments Segment Properties IK Constraints Segment Name Virtual Lab Segment Type Visual 3D ☒ Kinematic Only Create
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4. In the Virtual Lab tab, enter these values:	Define Proximal Joint and Radius Lateral: <i>None</i> Joint: <i>Lab_Z</i> Medial: <i>None</i> Radius: <i>0.01</i> Define Distal Joint and Radius Lateral: <i>None</i> Joint: <i>Lab_Origin</i> Medial: <i>None</i> Radius: <i>0.01</i> Extra Target to define Orientation Select: <i>Lateral Lab_Lateral</i> Select Tracking Targets: Check: <i>Use Calibration Targets for Tracking</i>	5. Click on Build Model. 6. Click on Close Tab before proceeding.	Workspace Signals and Events Models Reports CalT Segments Landmarks Muscles Subject Data / Metrics Segments Segment Properties IK Constraints Virtual Lab Define Proximal Joint and Radius Lateral: <i>None</i> Joint Center: <i>Lab_Z</i> Medial: <i>None</i> Radius (Meters): <i>0.001</i> Define Distal Joint and Radius Lateral: <i>None</i> Joint Center: <i>Lab Origin</i> Medial: <i>None</i> Radius (Meters): <i>0.001</i> Extra Target to Define Orientation (if needed) Location: <i>Lateral</i> <i>Lab Lateral</i> Select Tracking Targets (Ctrl-Left Mouse Click to Multiselect) ☒ Use Calibration Targets for Tracking Depth (Meters): Close Tab Guess Properties Apply Build Model
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We have just created a virtual lab that is aligned with the direction of progression of the subject.

Example: Virtual Lab Not Aligned with the Lab Axes

What if the subject is not walking along the lab axes? What if the subject is walking at a diagonal?

To calculate certain measures, such as the trunk angle relative to the lab, the virtual lab should be aligned with the subject's direction of progression. Although there are many methods to do this, some examples can be found [here](#).

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