This command is not available for common use.

Creates LinkModelBased joint rotations based on PSU IMU data.
Target 1 = origin
Target 2 = origin - (0,0,marker_distance)
Target 3 = origin + (0,marker_distance,0)

```
Joint_Rotations_From_PSU_IMU
/MOTION_FILE=
/FLOOR_FILE=
/SUBJECT_CAL_FILE=
/C3D_FILE=
;
```

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