

this command is not available for common use.

creates linkmodelbased joint rotations based on psu imu data.

target 1 = origin

target 2 = origin - (0,0,marker_distance)

target 3 = origin + (0,marker_distance,0)

```
joint_rotations_from_psu_imu
/motion_file=
/floor_file=
/subject_cal_file=
/c3d_file=
;
```

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