

creates 3 targets in a linkmodelbased rotation coordinate system.

target 1 = origin

target 2 = origin - (0,0,marker_distance)

target 3 = origin + (0,marker_distance,0)

```
create_targets_for_linkmodelbased_rotations
/signal_folders=
! /marker_distance=0.05
;
```

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Last update: 2024/06/19 12:50

