

Documentation

AMASS is a software package for deriving the three-dimensional (3D) locations of passive targets (unidentified markers) imaged by any number of video cameras, and writing the identified data to file using the [C3D file format](#).

Introduction

An introduction to the AMASS software system. [The AMASS shell program](#)

The main program that provides access to all AMASS functions and parameters. [Camera data conversion](#)

The conversion of raw camera data to *.cen* files used by AMASS. [ViewCen](#)

A utility for examining raw camera data *.cen* files. [Camera system calibration](#)

The very important camera system calibration process. [ViewLin](#)

The utility for examining the results of a calibration. [Tracking](#)

The automatic 3D reconstruction and tracking program. [ViewSeg](#)

A utility for displaying the continuity of reconstructed marker trajectories. [Identification basics](#)

An introduction to the marker trajectory labeling process. [Manual identification](#)

A simple method for labeling marker trajectories. [Identification_using_links](#)

The automated labeling of marker trajectories utilizing marker separations. [Analyze](#)

A utility to pass *.c3d* files to user specified analysis programs.

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