amass is a software package for deriving the three-dimensional (3d) locations of passive targets (unidentified markers) imaged by any number of video cameras, and writing the identified data to file using the c3d file format].

introduction

an introduction to the amass software system. **the amass shell program**

the main program that provides access to all amass functions and parameters. **camera data conversion**

the conversion of raw camera data to *.cen* files used by amass. **viewcen**

a utility for examining raw camera data *.cen* files. **camera system calibration**

the very important camera system calibration process. **viewlin**

the utility for examining the results of a calibration. **tracking**

the automatic 3d reconstruction and tracking program. **viewseg**

a utility for displaying the continuity of reconstructed marker trajectories. **identification basics**

an introduction to the marker trajectory labeling process. **manual identification**

a simple method for labeling marker trajectories. **identification_using_links**

the automated labeling of marker trajectories utilizing marker separations. **analyze**

a utility to pass *.c3d* files to user specified analysis programs.

From:
https://has-motion.com/wiki/ - **Wiki Documentation Site**

Permanent link:
https://has-motion.com/wiki/doku.php?id=other:amass:documentation&rev=1718804080

Last update: **2024/06/19 13:34**