

template tab]] automatically. the load from file button at the top left allows you to load a text file that holds the marker names and locations instead of entering the data manually. this text file can be created by pressing the [[caltester:caltesterplus:documentation:documentation_workspace#go|go button]] once the template data has been entered in the template mode's [[caltester:caltesterplus:documentation:documentation_template_tab#jig_options|template tab]]. the save to registry button at the top left allows you to save the coordinates that you have inputted as the default coordinate system. the add new template button allows you to have more than one template with individualized coordinate systems. ===== platform fp size ===== ctfpsize.png this screen allows you to specify the dimensions of the force platforms that you are using. these dimensions should be specified in the documentation provided by the force platform manufacture. you can add as many force platforms as you wish using the add new force button at the top left. to the right of the force platform list are the dialogue windows for length and width in meters. at the top of the screen is the save to registry button which makes the force platform dimensions that you have entered your default. } } } } } }

From:
<https://has-motion.com/wiki/> - Wiki Documentation Site

Permanent link:
https://has-motion.com/wiki/doku.php?id=caltester:caltesterplus:documentation:documentation_platform_tab&rev=1718803806

Last update: 2024/06/19 13:30

